GENERAL REPRESENTATIONS OF PSEUDOINVERSES

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Abstract. In this paper we investigate general representations of various classes of generalized inverses for bounded operators over Hilbert and Banach spaces. These representations are expressed by means of the full-rank decomposition of bounded operators and adequately selected operators.

1. Introduction

Let \mathcal{X}_1 and \mathcal{X}_2 denote arbitrary Banach spaces and $B(\mathcal{X}_1, \mathcal{X}_2)$ denote the set of all bounded operators from \mathcal{X}_1 into \mathcal{X}_2 . For an arbitrary operator $A \in B(\mathcal{X}_1, \mathcal{X}_2)$, we use $\mathcal{N}(A)$ to denote its kernel, and $\mathcal{R}(A)$ to denote its image.

For $A \in B(\mathcal{X}_1, \mathcal{X}_2)$ we say that an operator $X \in B(\mathcal{X}_2, \mathcal{X}_1)$ is a generalized inverse of A, provided that some of the following equations are satisfied:

$$(1) \quad AXA = A, \qquad (2) \quad XAX = X$$

If X satisfies the equation (1), then X is called a g-inverse of A. If X satisfies the equations (1) and (2), then it is called a reflexive g-inverse of A.

It is well-known that an operator $A \in B(\mathcal{X}_1, \mathcal{X}_2)$ has a g-inverse if and only if $\mathcal{R}(A)$ is closed, and $\mathcal{N}(A)$ and $\mathcal{R}(A)$, respectively, are complemented subspaces of \mathcal{X}_1 and \mathcal{X}_2 .

The notion of the full-rank decomposition for complex matrices is well-known and frequently used. Recall the definition of the full rank factorization for a bounded operator acting on Banach spaces from [2] and [3]:

Let $A \in B(\mathcal{X}_1, \mathcal{X}_2)$. If there exist: a Banach space \mathcal{X}_3 and operators $Q \in B(\mathcal{X}_1, \mathcal{X}_3)$ and $P \in B(\mathcal{X}_3, \mathcal{X}_2)$, such that P is left invertible, Q is right invertible and

$$A = PQ, (1.1)$$

then we say that (1.1) is the full-rank decomposition of A.

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It is well-known that an operator $A \in B(\mathcal{X}_1, \mathcal{X}_2)$ has the full-rank decomposition, if and only if A is g-invertible. In this case \mathcal{X}_3 is isomorphic to $\mathcal{R}(A)$, and $\mathcal{R}(A) = \mathcal{R}(P)$ [3].

We say that $A \in B(\mathcal{X})$ has the Drazin inverse, if there exists an operator $A^D \in B(\mathcal{X})$, such that A^D satisfies the equation (2) and the equations

$$(1^k) \quad A^{k+1}A^D = A^k, \qquad (5) \quad A^DA = AA^D,$$

for some non-negative integer k. Let us mention that the Drazin inverse, if it exists, is unique. The smallest k in the previous definition is called the index of A and denoted by $\operatorname{ind}(A)$. In the case $\operatorname{ind}(A) = 1$ the Drazin inverse is known as the group inverse of A, denoted by $A^{\#}$.

Recall that $\operatorname{asc}(A)$ (respectively $\operatorname{des}(A)$), the ascent (respectively descent) of A, is the smallest non-negative integer n, such that $\mathcal{N}(A^n) = \mathcal{N}(A^{n+1})$ (respectively $\mathcal{R}(A^n) = \mathcal{R}(A^{n+1})$). If no such n exists, then $\operatorname{asc}(A) = \infty$ (respectively $\operatorname{des}(A) = \infty$) [4]. It is well-known that A has the Drazin inverse, if and only1 if the ascent and descent of A are finite (hence, equal to $\operatorname{ind}(A)$) [3], [4].

In the case when \mathcal{H}_1 and \mathcal{H}_2 are Hilbert spaces, it is well-known that an operator $A \in B(\mathcal{H}_1, \mathcal{H}_2)$ has a g-inverse if and only if $\mathcal{R}(A)$ is closed. Among the equations (1), (2) we also consider the following equations in X:

(3)
$$(AX)^* = AX$$
, $(4) (XA)^* = XA$.

For a subset S of the set $\{1,2,3,4\}$, the set of operators obeying the conditions contained in S is denoted by $A\{S\}$. An operator in $A\{S\}$ is called an S-inverse of A and is denoted by $A^{(S)}$. If $\mathcal{R}(A)$ is closed, the set $A\{1,2,3,4\}$ consists of a single element, the Moore-Penrose inverse of A, denoted by A^{\dagger} .

We also consider the following equations, which define the weighted Moore-Penrose inverse:

$$(3M)$$
 $(MAX)^* = MAX$ $(4N)$ $(NXA)^* = NXA;$

$$(3M')$$
 $(AX)^*M = MAX$ $(4N')$ $(XA)^*N = NXA$

where $M \in B(\mathcal{H}_2)$, $N \in B(\mathcal{H}_1)$ are positive or invertible. Any solution of the equations (1), (2), (3M) and (4N), when it exists, will be denoted by $A_{M,N}^{\dagger}$. Similarly, any solution of the equations (1), (2), (3M') and (4N'), when it exists, will be denoted by $A_{M',N'}^{\dagger}$.

We investigate general representations and conditions for the existence of generalized inverses of bounded linear operatos on Hilbert spaces, arising from the factorization (1.1). As a related result we investigate some representations of a generalized inverse $A_{T,S}^{(2)}$. Obtained representations are generalizations of the analogous results available in the literature for marices. We also introduce a general representation and conditions for thye existence of the Drazin inverse of a bounded operator on a Banach space. There representations are based on the full-rank decomposition of A^l , where $l \geq \operatorname{ind}(A)$. Such an approach in representation of the Drazin inverse is not employed before even for complex matrices.

2. Results

Firstly, we investigate general representations of $\{1,2\}$ -inverses, $\{1,2,3\}$, $\{1,2,4\}$ -inverses, the Moore-Penrose and the weighted Moore-Penrose for operators in arbitrary Hilbert spaces.

We shall frequently use the following observation. If $S \in B(\mathcal{H}_1, \mathcal{H}_2)$ is onto, then SS^* is invertible and S^{\dagger} is the right inverse of S. Analogously, if $T \in B(\mathcal{H}_1, \mathcal{H}_2)$ is one-to-one with closed range, then T^*T is invertible and T^{\dagger} is the left inverse of T.

In the beginning, we state an analogy of the well-known result from [10, pp. 20, 28].

LEMMA 2.1. If A = PQ is the full-rank decomposition of $A \in B(\mathcal{H}_1, \mathcal{H}_2)$ according to (1.1), then:

- (a) Any right inverse of Q can be represented in the following form: $Q_r^{-1} = W_1(QW_1)^{-1}$, for an arbitrary operator $W_1 \in B(\mathcal{H}_3, \mathcal{H}_1)$ such that QW_1 is invertible
- (b) Any left inverse of P can be represented in the following form: $P_l^{-1} = (W_2P)^{-1}W_2$, for an arbitrary operator $W_2 \in B(\mathcal{H}_2, \mathcal{H}_3)$ such that W_2P is invertible.
- (c) Any reflexive generalized inverse X of A has the form $X=Q_r^{-1}P_l^{-1}$ for an arbitrary right inverse Q_r^{-1} of Q and an arbitrary left inverse P_l^{-1} of P.

In the literature there are known general representations for various classes of generalized inverses, for the set of complex matrices. The general representation of $\{1,2\}$ inverses for matrices is investigated in [9] and [10, pp. 20, 28]. The general representations of $\{1,2,3\}$ and $\{1,2,4\}$ inverses for matrices are investigated in [9]. In [6] there is given a general representation and conditions for the existence of the group inverse for a given complex matrix. The general representation of the Moore-Penrose inverse is given in [2], for arbitrary Hilbert spaces.

In the following theorem we give general representations of $\{1,2\}$, $\{1,2,3\}$ and $\{1,2,4\}$ inverses for an arbitrary bounded operator on Hilbert spaces. As a consequence we obtain the known representation of the Moore-Penrose inverse from [2].

Theorem 2.1. Let A = PQ be a full-rank decomposition of $A \in B(\mathcal{H}_1, \mathcal{H}_2)$ according to (1.1). Then:

(a) $X \in A\{1,2\}$ if and only if there exist operators $W_1 \in B(\mathcal{H}_3,\mathcal{H}_1)$ and $W_2 \in B(\mathcal{H}_2,\mathcal{H}_3)$, such that QW_1 and W_2P are invertible in $B(\mathcal{H}_3)$. In such a case, X possesses the following general representation

$$X = W_1(QW_1)^{-1}(W_2P)^{-1}W_2 (2.1)$$

(b) $X \in A\{1,2,3\}$ if and only if there exists an operator $W_1 \in B(\mathcal{H}_3,\mathcal{H}_1)$, such that QW_1 is invertible in $B(\mathcal{H}_3)$. In the case when it exists, a general representation for X is as follows:

$$X = W_1(QW_1)^{-1}(P^*P)^{-1}P^*. (2.2)$$

(c) $X \in A\{1,2,4\}$ if and only if there exists an operator $W_2 \in B(\mathcal{H}_2,\mathcal{H}_3)$, such that W_2P is invertible in $B(\mathcal{H}_3)$. In this case

$$X = Q^*(QQ^*)^{-1}(W_2P)^{-1}W_2.$$

(d) $A^{\dagger} = Q^{\dagger}P^{\dagger} = Q^{*}(QQ^{*})^{-1}(P^{*}P)^{-1}P^{*} = Q^{*}(P^{*}AQ^{*})^{-1}P^{*}$.

Proof. (a) Follows from Lemma 2.1.

(b) If X has the form (2.2), then it is easy to verify $X \in A\{1,2,3\}$. We need to prove that the form (2.2) holds for all $\{1,2,3\}$ inverses of A. Indeed, if $X \in A\{1,2,3\}$, then $X = Q_r^{-1}P_l^{-1}$, and from the equation (3) it follows that $(PP_l^{-1})^* = PP_l^{-1}$. Thus $P^*PP_l^{-1} = P^*$. Operator P^*P is invertible, so that $P_l^{-1} = (P^*P)^{-1}P^*$. The right inverse of Q retains the general form $Q_r^{-1} = W_1(QW_1)^{-1}$ from Lemma 2.1. Consequently,

$$X = W_1(QW_1)^{-1}(P^*P)^{-1}P^*.$$

The proof of the statement (c) is similar as the proof of (b). Also, (d) follows from (b) and (c). For the part (d) see also [2].

Now, we shall consider the weighted Moore-Penrose inverse under the various hypothesis. The weighted Moore-Penrose inverse is investigated in [1], [7] and [10] for the set of complex matrices and in [8] for matrices over an integral domain. If M and N are positive, then $A_{M,N}^{\dagger}$ and $A_{M',N'}^{\dagger}$ always exist [1], [10], and $A_{M,N}^{\dagger} = A_{M',N'}^{\dagger}$. In [8] and [7] it is derived a representation and conditions for the existence of $A_{M,N}^{\dagger}$ and $A_{M',N'}^{\dagger}$, respectively, under the more general assumptions that the matrices M and N are invertible (not necessary positive).

Theorem 2.2. Let A = PQ be a full-rank decomposition of A according to (1.1). Then:

(a) If $M \in B(\mathcal{H}_2)$ and $N \in B(\mathcal{H}_1)$ are invertible operators, then $A_{M,N}^{\dagger}$ exists if and only if P^*MP and $QN^{-1}Q^*$ are invertible selfadjoint operators. In that case

$$A_{M,N}^{\dagger} = N^{-1}Q^{*}(QN^{-1}Q^{*})^{-1}(P^{*}MP)^{-1}P^{*}M^{*}$$

$$= N^{-1}Q^{*}(Q(QN^{-1})^{*})^{-1}((MP)^{*}P)^{-1}(MP)^{*}.$$
(2.3)

(b) Let $M \in B(\mathcal{H}_2)$ and $N \in B(\mathcal{H}_1)$ be invertible operators, such that $QN^{-1}Q^*$ is left invertible and P^*MP right invertible. Then $A^{\dagger}_{M',N'}$ exists if and only if $QN^{-1}Q^*$ and P^*MP are invertible and

$$E = N^{-1}Q^*(QN^{-1}Q^*)^{-1} = (QN^{-1})^*(Q(QN^{-1})^*)^{-1},$$

$$F = (P^*MP)^{-1}P^*M = ((MP)^*P)^{-1}(MP)^*.$$
(2.4)

In this case is $A^{\dagger}_{M',N'}=Q^{-1}_rP^{-1}_l$, where $Q^{-1}_r=E$ and $P^{-1}_l=F$.

(c) If $M \in \mathcal{B}(\mathcal{H}_2)$ and $N \in \mathcal{B}(\mathcal{H}_1)$ are positive and invertible operators, then

$$\begin{split} A_{M,N}^{\dagger} &= A_{M',N'}^{\dagger} = (QN^{-1})^*(Q(QN^{-1})^*)^{-1}((MP)^*P)^{-1}(MP)^* \\ &= N^{-1}Q^*(QN^{-1}Q^*)^{-1}(P^*MP)^{-1}P^*M. \end{split} \tag{2.5}$$

Proof. (a) If M and N are invertible operators and $A_{M,N}^{\dagger}$ exists, using the principles from [8], from (3M) and (4N) we get

$$P^*MPP_l^{-1} = P^*M^*, \qquad Q_r^{-1}Q(N^{-1})^*Q^* = N^{-1}Q^*, \tag{2.6}$$

$$P^*MP = P^*M^*P,$$
 $QN^{-1}Q^* = Q(N^{-1})^*Q^*.$ (2.7)

From (2.7) we conclude that P^*MP and $QN^{-1}Q^*$ are selfadjoint operators. We now prove that $P^*MP = P^*M^*P$ and $QN^{-1}Q^* = Q(N^{-1})^*Q^*$ are invertible. Indeed, from (1) and (3M) we get the following equation (see [8]):

$$(QXM^{-1}X^*Q^*)(P^*M^*P) = I.$$

This means that P^*M^*P is left invertible. Also, since P^*M^*P is selfadjoint, we conclude that P^*M^*P is invertible. Similarly, (1) and (4N) imply the following

$$(QN^{-1}Q^*)(P^*X^*N^*XP) = I,$$

which means that $QN^{-1}Q^*$ is right invertible, so it is also invertible.

Using invertibility of $QN^{-1}Q^*$ and P^*M^*P , from (2.6) it follows

$$P_l^{-1} = (P^*M^*P)^{-1}(MP)^*, \quad Q_r^{-1} = N^{-1}Q^*(Q(N^{-1})^*Q^*)^{-1}.$$
 (2.8)

Now, the representations (2.3) follows from $A_{M,N}^{\dagger} = Q_r^{-1} P_l^{-1}$, (2.8) and (2.7).

(b) Suppose that $M \in B(\mathcal{H}_2)$ and $N \in B(\mathcal{H}_1)$ are invertible operators, such that $QN^{-1}Q^*$ is left invertible and P^*MP right invertible and $A^{\dagger}_{M',N'}$ exists. From the equations (1) and (3M') in the same way as in [7] we get $(QXM^{-1}X^*Q^*)(P^*MP) = I$, which means that P^*MP is left invertible. Similarly, from (1) and (4N') we obtain $(QN^{-1}Q^*)(P^*X^*NXP) = I$, which implies the right invertibility of $QN^{-1}Q^*$. According to the assumptions, we conclude that P^*MP and $QN^{-1}Q^*$ are invertible. The identities (2.4) can be proved using the method from [7].

On the other hand, if P^*MP and $QN^{-1}Q^*$ are invertible and (2.4) holds, one can verify that $Q_r^{-1}P_l^{-1}$ (where $Q_r^{-1}=E$ and

 $P_l^{-1}=F)$ satisfies the equations which define $A_{M',N'}^\dagger.$

(c) Firstly, we prove that $Q(QN^{-1})^*$ and $(MP)^*P$ are positive and invertible in $B(\mathcal{H}_3)$. If $x \in \mathcal{H}_3$ and ||x|| = 1, then

$$(Q(QN^{-1})^*x, x) = (N^{-1}Q^*x, Q^*x) > 0.$$

Suppose that $\inf_{\|x\|=1} (Q(QN^{-1})^*x, x) = 0$. Then there exists a sequence of unit vectors $(x_n)_n$ in \mathcal{H}_3 , such that $\lim_n (N^{-1}Q^*x_n, Q^*x_n) = 0$. Since N^{-1} is positive and invertible, it follows that there exists a subsequence $(x_{n_k})_k$ of $(x_n)_n$, such that $\lim_k Q^*x_{n_k} = 0$. Now, it follows that Q^* is not one-to-one with closed range, so Q is not onto. We get the contradiction, so $Q(QN^{-1})^*$ is positive and invertible

in $B(\mathcal{H}_3)$. Analogously, we can prove that $(MP)^*P$ is positive and invertible in $B(\mathcal{H}_3)$.

The rest of the proof follows from parts (a) and (b). ■

Now, we consider {2}-generalized inverses with prescribed range and kernel. Fundamental results for matrices can be found in [1] and [5].

Let $A \in B(\mathcal{H}_1, \mathcal{H}_2)$ and $X \in B(\mathcal{H}_2, \mathcal{H}_1)$ be a $\{2\}$ -inverse of A, such that $\mathcal{R}(X) = T$ is a closed subspace of \mathcal{H}_1 and $\mathcal{N}(X) = S$ is a closed subspace of \mathcal{H}_2 . Then we write $X = A_{T,S}^{(2)}$. For given closed subspaces T of \mathcal{H}_1 and S of \mathcal{H}_2 , it is a natural question when $A_{T,S}^{(2)}$ exists? The answer in the case of arbitrary Hilbert spaces is given in the following theorem.

We state the following elementary result.

LEMMA 2.2. Let $A \in B(\mathcal{H}_1, \mathcal{H}_2)$, T and S be closed subspaces of \mathcal{H}_1 and \mathcal{H}_2 respectively. Then the following statements are equivalent:

- (a) A has a $\{2\}$ -inverse $X \in B(\mathcal{H}_2, \mathcal{H}_1)$ such that $\mathcal{R}(X) = T$ and $\mathcal{N}(X) = S$;
- (b) $A: T \to A(T)$ is invertible and $A(T) \oplus S = \mathcal{H}_2$.

In the case when (a) or (b) holds, X is unique and is denoted by $A_{T.S.}^{(2)}$

Now, we generalize the result from [5].

THEOREM 2.3. Suppose that A, T and S satisfy the condition (a) or (b) from Lemma 2.2 and let $Y \in B(\mathcal{H}_2, \mathcal{H}_1)$ be such that $\mathcal{R}(Y) = T$ and $\mathcal{N}(Y) = S$. If there exists a Hilbert space \mathcal{H}_3 and a left invertible operator $E \in B(\mathcal{H}_3, \mathcal{H}_1)$ such that $\mathcal{R}(E) = T$, then

$$W = E^*YAE \in B(\mathcal{H}_3)$$

is invertible in $B(\mathcal{H}_3)$ and

$$A_{T,S}^{(2)} = EW^{-1}E^*Y.$$

Proof. Notice that $E: \mathcal{H}_3 \to T$ is invertible, $A: T \to AT$ is inverible and $Y: AT \to T$ is invertible. Since $\mathcal{N}(E^*)^{\perp} = \mathcal{R}(E) = T$, it follows that $E^*: T \to \mathcal{H}_3$ is invertible, so W is invertible. Now, it is easy to verify that $EW^{-1}E^*Y$ is a $\{2\}$ -inverse of A. Also, $\mathcal{N}(Y) = S$, $W^{-1}E^*Y: AT \to \mathcal{H}_3$ is invertible and $\mathcal{R}(EW^{-1}E^*Y) = \mathcal{R}(E) = T$, $\mathcal{N}(EW^{-1}E^*Y) = S$, so

$$A_{T,S}^{(2)} = EW^{-1}E^*Y$$
.

THEOREM 2.4. Let $A: \mathcal{H}_1 \to \mathcal{H}_2$ and $X: \mathcal{H}_2 \to \mathcal{H}_1$. Then $X \in A\{2\}$ if and only if there exist Hilbert spaces \mathcal{H}_3 , \mathcal{H}_4 , \mathcal{H}_5 and operators

$$C \in B(\mathcal{H}_4, \mathcal{H}_1), D \in B(\mathcal{H}_2, \mathcal{H}_3), W_1 \in B(\mathcal{H}_5, \mathcal{H}_4), W_2 \in B(\mathcal{H}_3, \mathcal{H}_5),$$

such that DAC is g-invertible and W_2DACW_1 is invertible. In this case:

$$X = CW_1(W_2DACW_1)^{-1}W_2D. (2.9)$$

Proof. If X possesses the form (2.9), it is not difficult to verify $X \in A\{2\}$. On the other hand, using the method from [10], it is easy to verify that $X \in A\{2\}$ if and only if there exist operators C and D, such that

$$X = C(DAC)^{(1,2)}D, C \in B(\mathcal{H}_4, \mathcal{H}_1), D \in B(\mathcal{H}_2, \mathcal{H}_3).$$

According to part (a) of Theorem 2.1, $X \in A\{2\}$ if and only if there exist operators W_1 and W_2 , such that W_2DACW_1 is invertible, and X possesses the form (2.9).

We introduce a general representation of the Drazin inverse based on an arbitrary full-rank factorization of A^l , $l \ge k = \mathrm{asc}(A) = \mathrm{des}(A)$. The following theorem is a natural generalization of a Cline's result from [6], introduced for complex matrices. We shall assume that A is not a nilpotent operator, i.e. $A^D \ne 0$.

Theorem 2.5. Let \mathcal{X} be a Banach space. If $A \in B(\mathcal{X})$, $l \geq k = \mathrm{asc}(A) = \mathrm{des}(A) < \infty$ and $A^l = P_{A^l}Q_{A^l}$ is the full-rank decomposition of A^l , then

$$A^D = P_{A^l} (Q_{A^l} A P_{A^l})^{-1} Q_{A^l}.$$

Proof. If $\operatorname{asc}(A) = \operatorname{des}(A) = k < \infty$, then it is well-known that $\mathcal{N}(A^l) = \mathcal{N}(A^k)$ and $\mathcal{R}(A^l) = \mathcal{R}(A^k)$ for all $l \geq k$,

$$\mathcal{X} = \mathcal{X}_1 \oplus \mathcal{X}_2, \tag{2.10}$$

where $\mathcal{X}_1 = \mathcal{N}(A^l)$ and $\mathcal{X}_2 = \mathcal{R}(A^l)$, $A(\mathcal{X}_i) \subset \mathcal{X}_i$ for $i = 1, 2, A_1 = A|_{\mathcal{X}_1}$ is nilpotent and $A_2 = A|_{\mathcal{X}_2}$ is invertible (A is not nilpotent) [3], [4]. We can write

$$A = \begin{bmatrix} A_1 & 0 \\ 0 & A_2 \end{bmatrix}, \qquad A^D = \begin{bmatrix} 0 & 0 \\ 0 & A_2^{-1} \end{bmatrix}$$

with respect to the decomposition (2.10) ([3], [4]). Since $\mathcal{N}(A^l)$ and $\mathcal{R}(A^l)$ are complementary and closed subspaces of \mathcal{X} , it follows that A^l is g-invertible, so there exists the full-rank decomposition $A^l = P_{A^l}Q_{A^l}$, where $P_{A^l} \in B(\mathcal{Z}, \mathcal{X})$ is left invertible and $Q_{A^l} \in B(\mathcal{X}, \mathcal{Z})$ is right invertible, for some Banach space \mathcal{Z} . By the isomorphism theorem [3], we can take that $\mathcal{Z} = \mathcal{X}_2$. We conclude that P_{A^l} and Q_{A^l} have the following representations with respect to (2.10):

$$P_{A^l} = \left[egin{array}{c} M \ ilde{P} \end{array}
ight] \qquad ext{and} \qquad Q_{A^l} = \left[egin{array}{c} N & ilde{Q} \end{array}
ight],$$

where $\tilde{P}, \tilde{Q} \in B(\mathcal{X}_2), M \in B(\mathcal{X}_2, \mathcal{X}_1), N \in B(\mathcal{X}_1, \mathcal{X}_2)$. Now, P_{A^l} is left invertible and Q_{A^l} is right invertible, so P_{A^l} and Q_{A^l} are g-invertible operators, $\mathcal{N}(P_{A^l}) = \{0\}$ and $\mathcal{R}(Q_{A^l}) = \mathcal{X}_2$. It follows that $\mathcal{R}(P_{A^l}) = \mathcal{R}(A^l) = \mathcal{X}_2$ and $\mathcal{N}(Q_{A^l}) = \mathcal{N}(A^l) = \mathcal{X}_1$, so M = 0, N = 0 and

$$P_{A^l} = \left[egin{array}{c} 0 \ ilde{P} \end{array}
ight] \qquad ext{and} \qquad Q_{A^l} = \left[egin{array}{c} 0 & ilde{Q} \end{array}
ight].$$

It is easy to verify that \tilde{P} is left invertible and \tilde{Q} is right invertible in $B(\mathcal{X}_2)$. But

$$\begin{bmatrix} 0 & 0 \\ 0 & A_2^l \end{bmatrix} = A^l = P_{A^l} Q_{A^l} = \begin{bmatrix} 0 & 0 \\ 0 & \tilde{P} \tilde{Q} \end{bmatrix},$$

so $A_2^l = \tilde{P}\tilde{Q}$. Since A_2^l is invertible, it follows that \tilde{P} and \tilde{Q} are invertible in $B(\mathcal{X}_2)$.

Now, $Q_{A^l}AP_{A^l} = \tilde{Q}A_2\tilde{P}$ is invertible in $B(\mathcal{X}_2)$, so

$$A^D = \begin{bmatrix} 0 & 0 \\ 0 & A_2^{-1} \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & \tilde{P}(\tilde{Q}A_2\tilde{P})^{-1}\tilde{Q} \end{bmatrix} = P_{A^l}(Q_{A^l}AP_{A^l})^{-1}Q. \quad \blacksquare$$

As a corollary, we get the following result.

Corollary 2.1. If \mathcal{X} is a Banach space, $A \in B(\mathcal{X})$ and $\operatorname{asc}(A) = \operatorname{des}(A) = k < \infty$ and $A^l = P_{A^l}Q_{A^l}$ is an arbitrary full-rank decomposition of A^l , $l \geq k$, then

- (a) $(A^D)^l = P_{A^l}(Q_{A^l}A^lP_{A^l})^{-1}Q_{A^l} = P_{A^l}(Q_{A^l}P_{A^l})^{-2}P_{A^l};$
- (b) $AA^D = P_{A^l}(Q_{A^l}P_{A^l})^{-1}Q_{A^l};$
- (c) If \mathcal{X} is a Hilbert space, then $(A^D)^{\dagger} = (Q_{A^l})^{\dagger} Q_{A^l} A P_{A^l} (P_{A^l})^{\dagger}$.

Proof. (a) Follows from $(A^D)^l = (A^l)^\#$ and Theorem 2.5.

(b) According to Theorem 2.5 it follows that $Q_{A^l}P_{A^l}=\tilde{Q}\tilde{P},$ so an easy computation shows that

$$P_{A^l}(Q_{A^l}P_{A^l})^{-1}Q_{A^l} = \begin{bmatrix} 0 & 0 \\ 0 & I \end{bmatrix} = AA^D.$$

(c) Follows from Theorem 2.1 (d) and Theorem 2.5. ■

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